## FUNDAMENTALS OF AVIONICS

## **OPEN ELECTIVE - I**

Course Code		Catagory	Hours / Mask			Cradita	Messimum Merke		
A5AE62		Category OEC	HO			Credits C	Maximum Marks		
			3		<b>C</b> 3	30	70	<b>Total</b> 100	
engineering 1. Overvie 2. Basic u	e of this s application w on Aviati nderstandir	subject is to provide t	nics sys	stems	used fo	r communio	cation	-	nd
UNIT-I	BASICS	& FLIGHT DECK A	ND DI	SPLA	AY SYS	STEMS			
vehicles. FLIGHT DE		bles of Avionics, Typic DISPLAY SYSTEMS: ay, electronic instrumer	Flight	deck	display		•		•
UNIT-II	COMMU	INICATION SYSTEM	IS						
		UNICATION SYSTEM F communication syste						dio transi	mitter an
	nciples, VH		em, UH	F com				dio transi	mitter an
receiver prir UNIT-III RANGING equipment, POSITIONG	AND LAN PREQUI AND LAN principles c SYSTEI	F communication system ENCY RANGING SY DING SYSTEMS: VH of operation, Instrumen M: Global positioning	em, UH <b>′STEN</b> F Omr t landir	F com I nirange ng sys	e, VOR	receiver p d localizer a	ns. principles and glide	s, distanc slope.	e maturit
UNIT-III RANGING equipment,	AND LAN Principles of SYSTEI	F communication system ENCY RANGING SY DING SYSTEMS: VH of operation, Instrumen M: Global positioning	em, UH <b>′STEN</b> F Omr t landir	F com I nirange ng sys	e, VOR	receiver p d localizer a	ns. principles and glide	s, distanc slope.	e maturit
receiver prin UNIT-III RANGING equipment, POSITIONG applications UNIT-IV INERTIAL M inertial Navi SURVELLIE	AND LAN FREQUI AND LAN principles of SYSTEI in aviation NAVIGATIO gation syst ENCE SYS	F communication system ENCY RANGING SY DING SYSTEMS: VH of operation, Instrumen M: Global positioning	em, UH <b>STEN</b> F Omr t landir g sys e of Op gyros a e syste	F com I nirange ng sys tem eration and sta ms pr	e, VOR tem, an principle	receiver p d localizer a es, triangu a, navigation platform. and opera	ns. principles and glide ilation, n over ea	s, distanc e slope. position arth, com	e maturit accuracy
receiver prin UNIT-III RANGING equipment, POSITIONG applications UNIT-IV INERTIAL M inertial Navi SURVELLI	AND LAN PREQUI AND LAN principles of SYSTEI in aviation NAVIGATIO gation syst ENCE SYS Collision av	F communication syste ENCY RANGING SY DING SYSTEMS: VH of operation, Instrumen M: Global positioning TION SYSTEM DN SYSTEM: Principle ems, accelerometers, g TEM: ATC surveillance	em, UH <b>STEN</b> F Omr t landir g sys e of Op gyros a e syste	F com I nirange ng sys tem eration and sta ms pr	e, VOR tem, an principle	receiver p d localizer a es, triangu a, navigation platform. and opera	ns. principles and glide ilation, n over ea	s, distanc e slope. position arth, com	e maturit accuracy
receiver prir UNIT-III RANGING equipment, POSITIONG applications UNIT-IV INERTIAL N inertial Navi SURVELLIE standards, C UNIT-V AUTO FLIG	AND LAN PREQUI AND LAN principles of SYSTER SYSTER SYSTER NAVIGATIO Gation syst ENCE SYS Collision av AUTO F GHT SYSTER	F communication syste ENCY RANGING SY DING SYSTEMS: VH of operation, Instrumen M: Global positioning TION SYSTEM DN SYSTEM: Principle ems, accelerometers, g TEM: ATC surveillance oidance system, groun	em, UH <b>STEN</b> F Omr t landir g sys e of Op gyros a e syste id prox	F com inirange ng sys tem eratior and sta ms pr imity v	e, VOR tem, an principle bilized inciples varning	receiver p d localizer a es, triangu and opera system	ns. principles and glide ilation, n over ea tion inter	s, distanc e slope. position arth, com	e maturit accuracy ponents o and repla
receiver prir UNIT-III RANGING equipment, POSITIONG applications UNIT-IV INERTIAL N inertial Navi SURVELLIE standards, ( UNIT-V AUTO FLIG director syst Text Book	AND LAN PREQUI AND LAN principles of SYSTER SYSTER SYSTER NAVIGATIO GAUTO F Collision av AUTO F Collision av AUTO F Collision av Collision av	F communication syste ENCY RANGING SY DING SYSTEMS: VH of operation, Instrumen M: Global positioning TION SYSTEM: Principle ems, accelerometers, g TEM: ATC surveillance oidance system, groun CLIGHT SYSTEM EM: Automatic flight co management systems	em, UH <b>STEN</b> F Omr t landir g sys of Op gyros a e system of prox ontrol sy	F com inirange ng sys tem eratior and sta ms pr imity v ystems	e, VOR tem, an orinciple bilized inciples varning	receiver p d localizer a es, triangu and opera system wire and fly	ns. principles and glide ilation, n over ea tion inter	s, distanc e slope. position arth, com rogation	e maturi accurac ponents and repla
receiver prin UNIT-III RANGING equipment, POSITIONG applications UNIT-IV INERTIAL M inertial Navi SURVELLIE standards, ( UNIT-V AUTO FLIG director syst Text Book	AND LAN FREQUI AND LAN principles of SYSTEI in aviation NAVIGATIO gation syst ENCE SYS Collision av AUTO F GHT SYSTE tems, flight S. Nagaraja	F communication syste ENCY RANGING SY DING SYSTEMS: VH of operation, Instrumen M: Global positioning TION SYSTEM DN SYSTEM: Principle ems, accelerometers, g TEM: ATC surveillance oidance system, groun CLIGHT SYSTEM EM: Automatic flight co	em, UH <b>STEN</b> F Omr t landir g sys of Op gyros a e system of prox ontrol sy	F com inirange ng sys tem eratior and sta ms pr imity v ystems	e, VOR tem, an orinciple bilized inciples varning	receiver p d localizer a es, triangu and opera system wire and fly	ns. principles and glide ilation, n over ea tion inter	s, distanc e slope. position arth, com rogation	e maturit accuracy ponents o and repla

- 1. Albert Hel Frick (2010), Principle of Avionics, 6th edition, Avionics Communications Inc, India.
- 2. H. J. Pallet (2010), Aircraft Instrumentation and Integrated systems, Pearson Education, New Delhi.
- 3. J. Powell (1998), Aircraft Radio Systems, Pitman publishers, London

## COURSE OUTCOMES:

At the end of the course the students are able to:

- 1 To explain the instrumentation used in avionics.
- 2 To classify various ranges of the communication techniques used in aircraft.
- 3 To distinguish between network systems, controlling parts & surfaces
- 4 To compare various principles of navigation systems
- 5 To build phenomena of auto pilot control system